

Quantitative logics

David N. Jansen

Objectives

**overview over quantitative logics
and (probabilistic) model checking**

Objectives

- express requirements and create behaviour models
- know possibilities and limitations of model checking
- know a variety of quantitative logics and their model checking algorithms
- You could write (the mathematical logic part of) a simple model checker.
- ~~optimisation methods (BDDs, symbolic model checking)~~
- ~~solve linear equation systems~~

Practical matters

- website:
https://lab.cs.ru.nl/algemeen/Quantitative_logics
- exercises: no obligations
- written exam

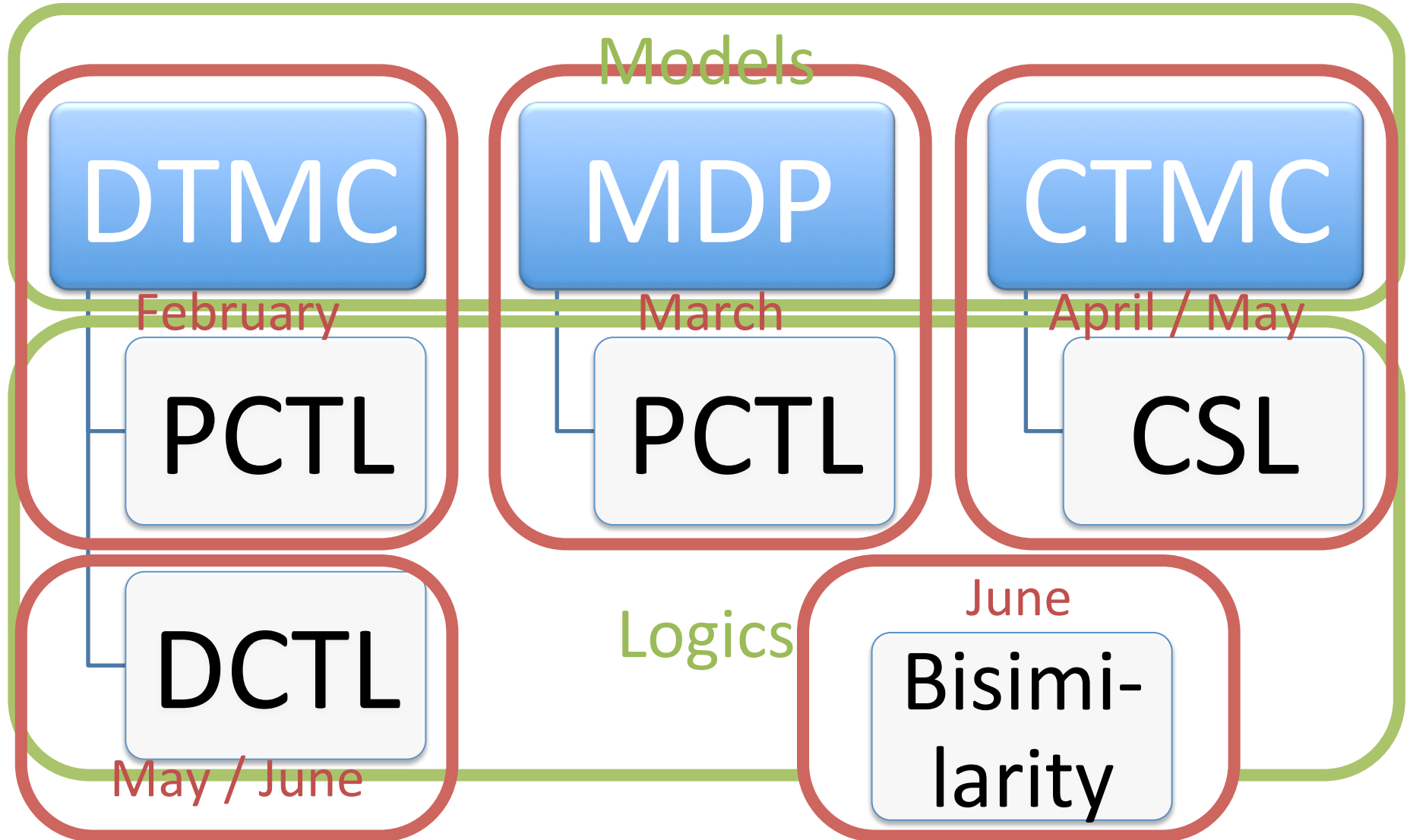
What do you know already?

- model checking?
- probability theory?
- Markov chains?
- temporal logic?

Today's programme

- General overview
- Temporal logic
- Model checking basics
- Probability theory basics

Global overview



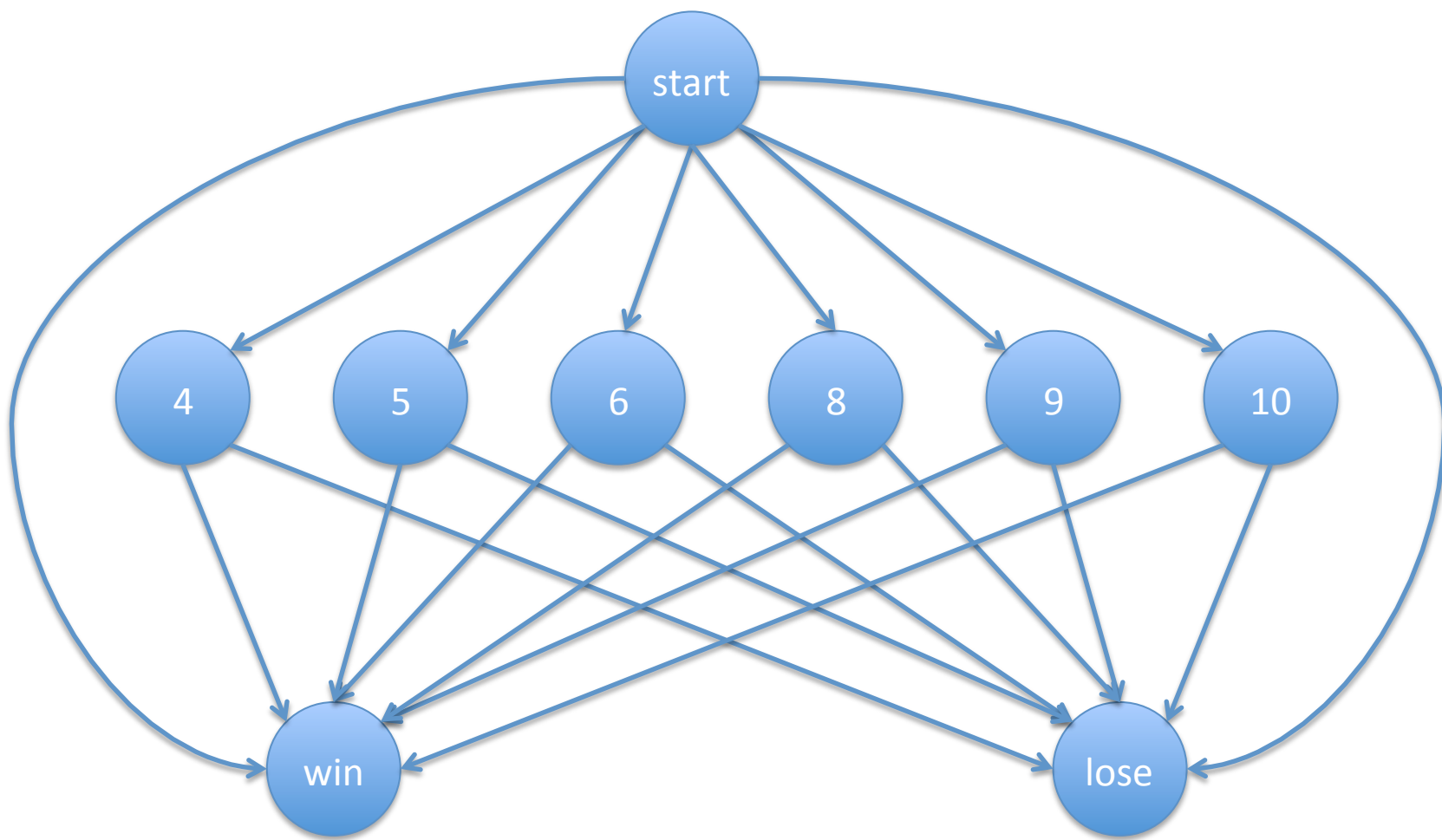
Models

- extensions of transition systems
 - discrete state space
 - transitions describe possible behaviours
- probabilistic choice between transitions
- CTMC: stochastic timing
(probability distribution over how long a state lasts)

Example model:

Craps game

- throw two dice and sum them
 - 7, 11: win immediately
 - 2, 3, 12: lose immediately
 - other result: this result is “point”
- throw the dice until the result is:
 - 7: lose
 - point: win
- can be modelled as a DTMC



Temporal logic

Principles

- want to describe properties of behaviours
 - behaviour := sequence of computation steps
- extend propositional logic
 - use propositions to describe one state
- modality operators:
 - at some time \diamond $F_{(uture)}$
 - always \square $G_{(enerally)}$

CTL: additional modalities

- modality operators:
 - at some time \diamond $F_{(uture)}$
 - always \square $G_{(enerally)}$

 - in some future E
 - in all futures A

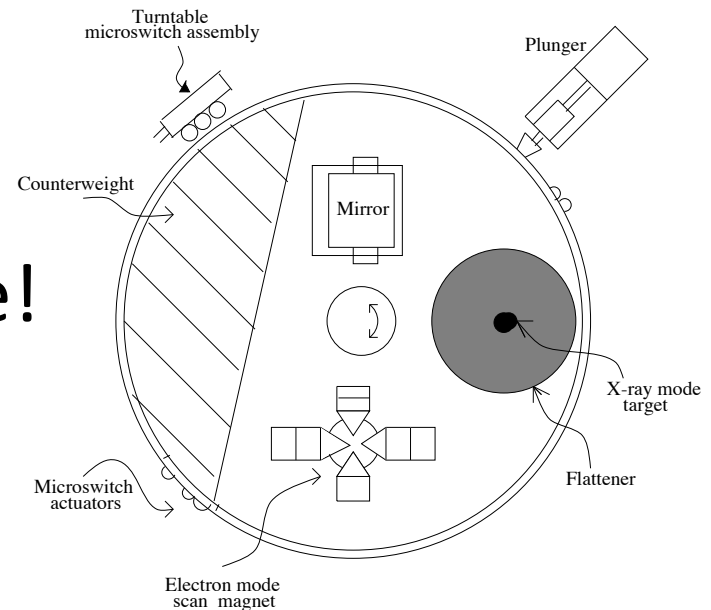
Examples: mutual exclusion

- Propositions:
 - $crit_i$ component i is in critical section
 - try_i component i wants to enter critical section
- It will never happen that both components are in their critical sections.
- In every state, a component may eventually enter its critical section.
- Whenever a component tries to enter its critical section, it will do so eventually.

Model checking basics

Why model checking?

- Therac-25: a medical irradiation device with deadly software
- generates electron beam
- can be converted to X-rays
 - about 1% efficiency
- wrong position → overdose!
- ≥ 5 patients deceased



System verification

- solves **some** problems with software correctness
- verification:
check whether system meets specification
- silent assumption: specification is correct
+ model behaves as system

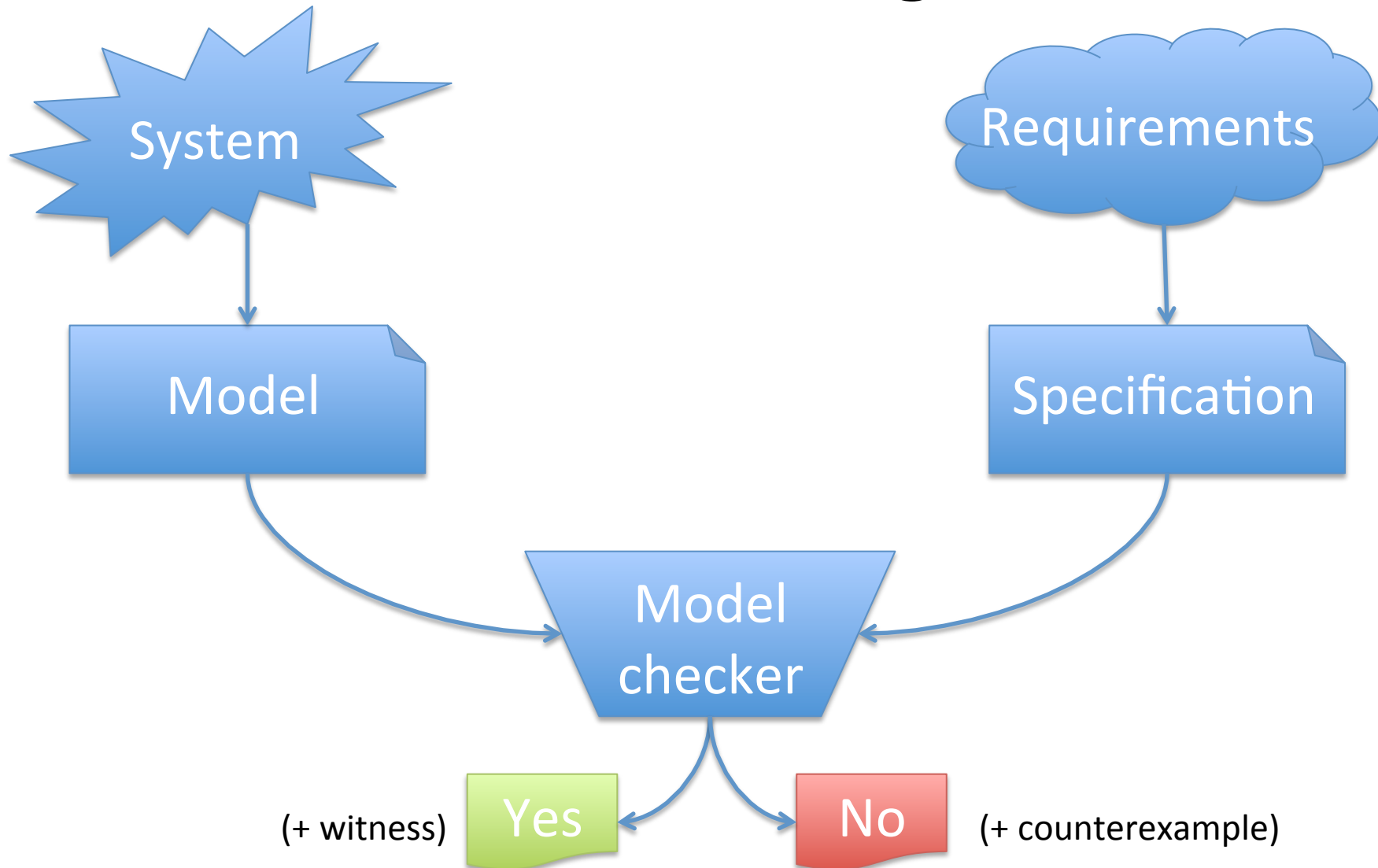
Formal system verification

- use mathematics to model and analyse ICT systems
- two main methods:
 - deductive proof
 - system model is a mathematical theory
 - often computer-assisted
 - model checking
 - system model is a finite automaton (or similar)
 - in principle fully automatic

Model checking: idea

- create a model of the behaviour
- specify desired behaviours
- look for a formal proof (automatically)
 - (proof rules should be simple enough that provability is decidable)

Model checking: idea



Property specification language: temporal logic

- typical properties:
 - Can the system reach a deadlock?
 - Can two processes be in the critical section?
 - Is the output correct upon termination?
- standard property:
 - Can the system reach an undesired state?
 - Will the system reach a desired state?

Mutual exclusion

- Requirements in CTL

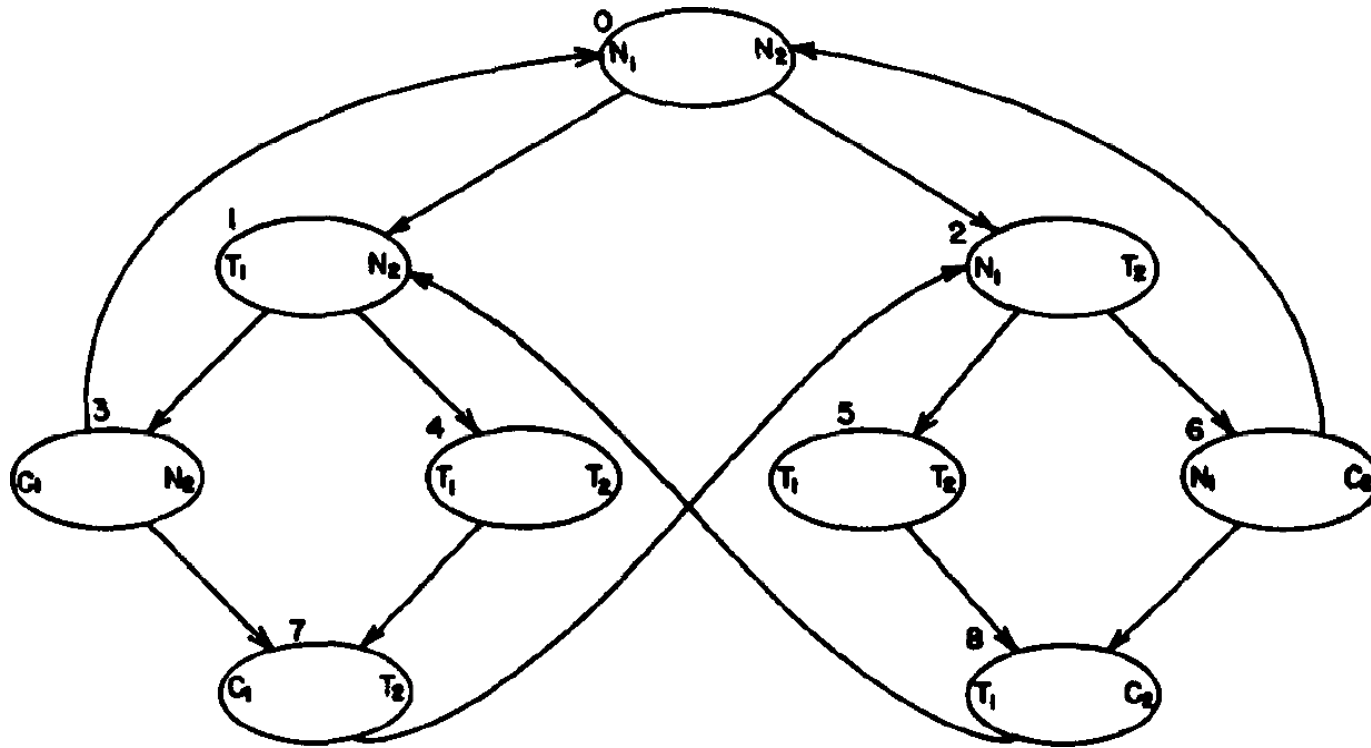
„If process 1 tries to execute its critical section (T_1), it will eventually enter it (C_1).“

$$T_1 \rightarrow A \diamond C_1$$

- Subformulas:

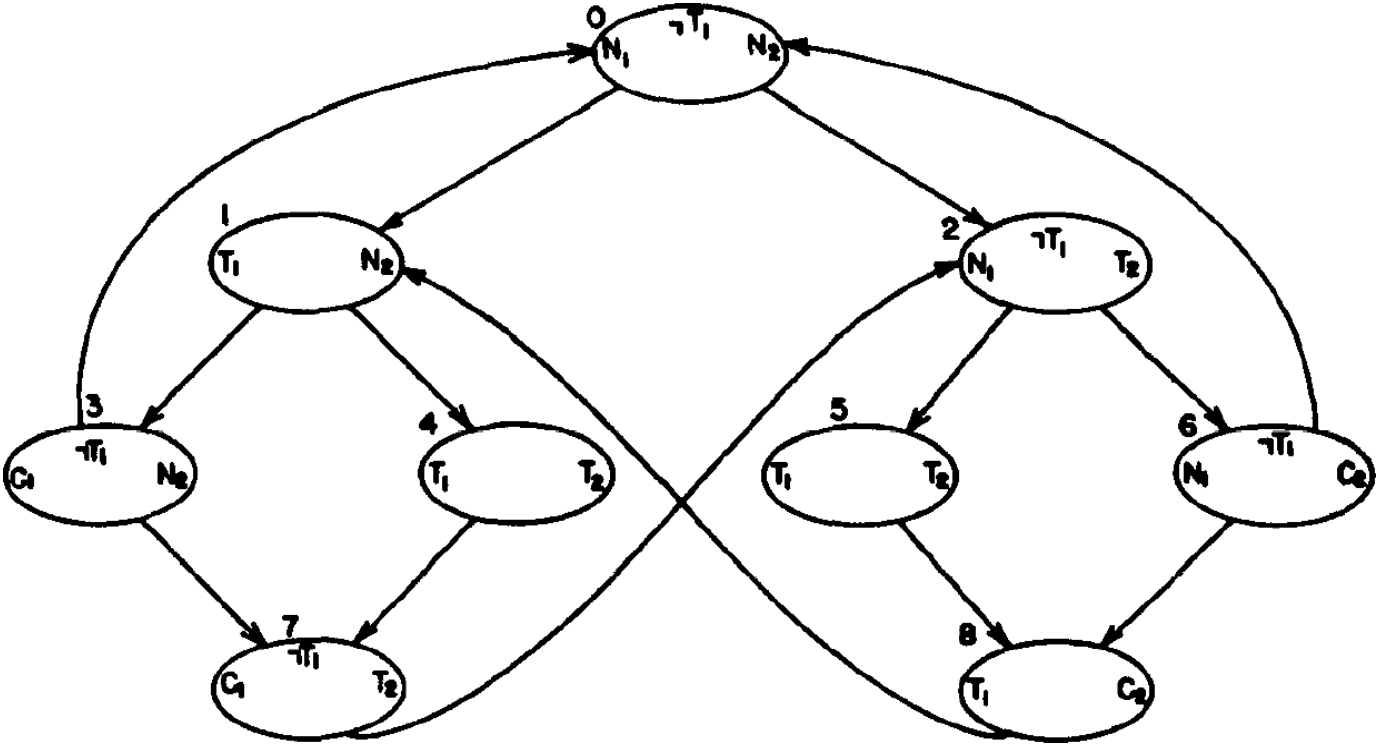
$$T_1 \quad C_1 \quad \neg T_1 \quad A \diamond C_1 \quad \neg T_1 \vee A \diamond C_1$$

Model checking



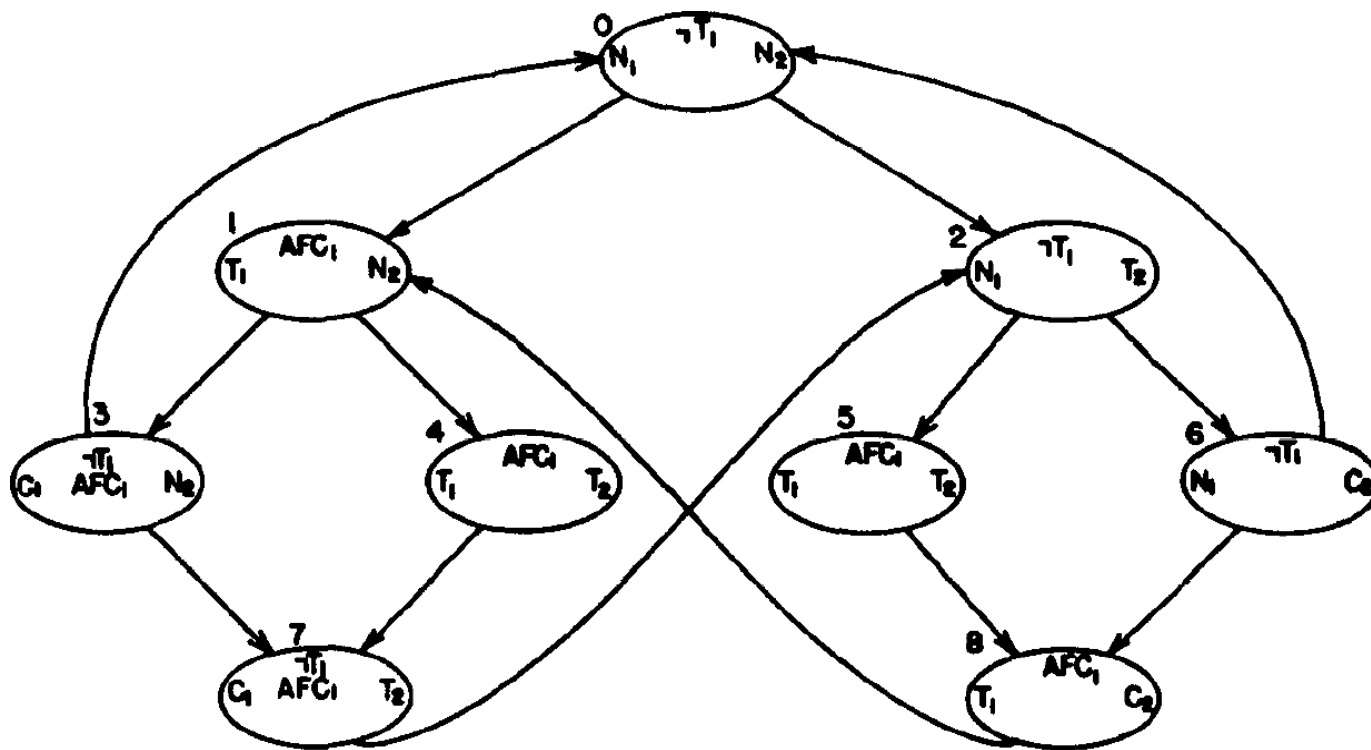
$$\neg T_1 \vee A \diamond C_1$$

Model checking



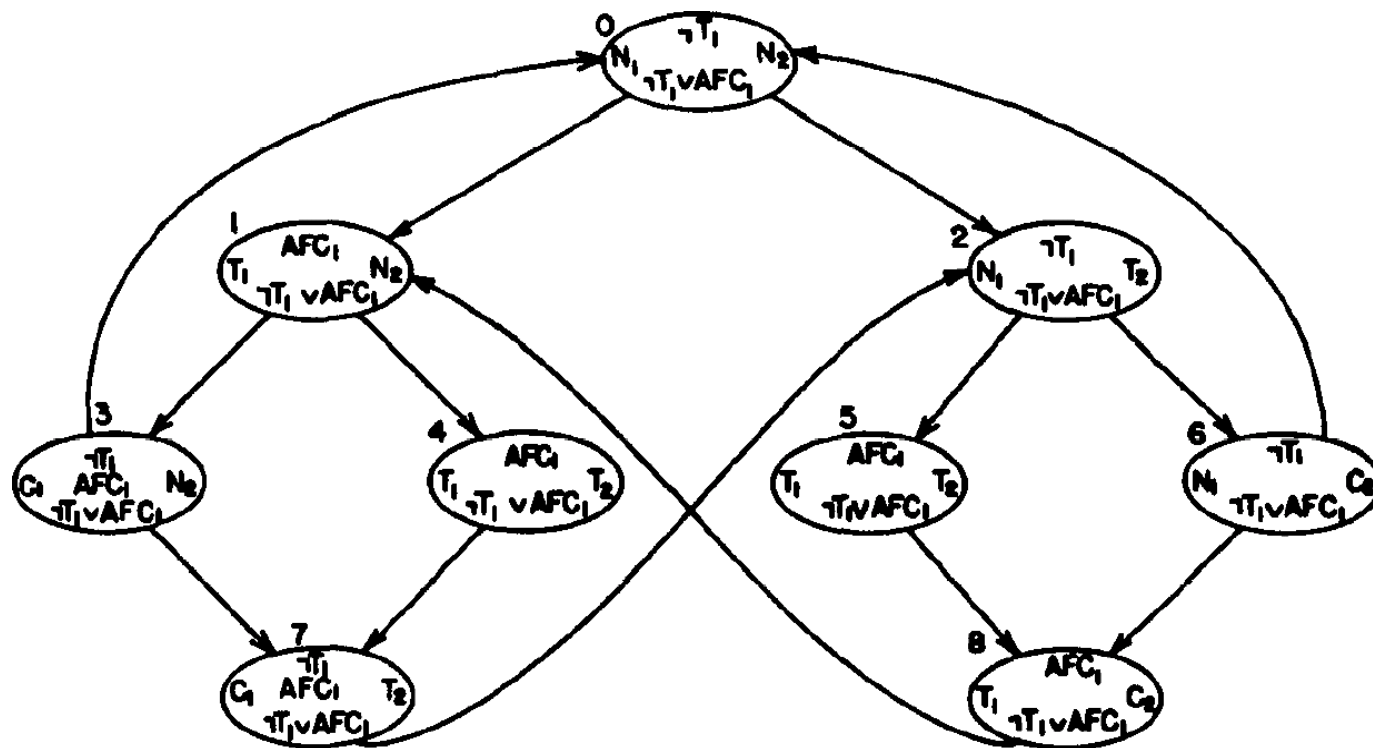
$$\neg T_1 \vee A \diamond C_1$$

Model checking



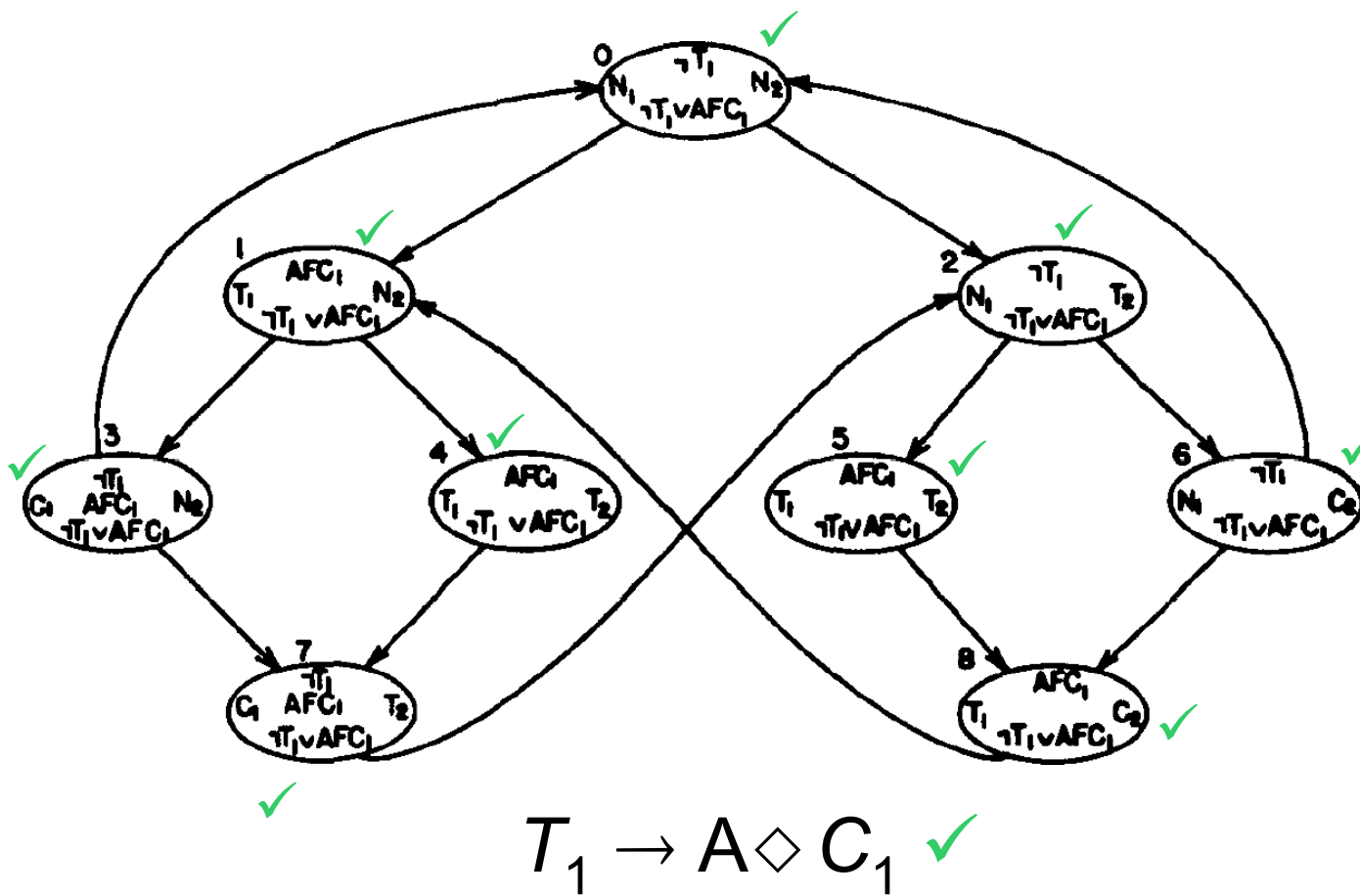
$$\neg T_1 \vee A \diamond C_1$$

Model checking



$$\neg T_1 \vee A \diamond C_1$$

Model checking



Recapitulation

- System verification makes sure the system satisfies its specification.
- Model checking is a method for system verification, (in principle) fully automatic.
- Model checking reads
 - a behavioural system model (transition system)
 - a property (temporal logic)

Probability theory

What are probabilities?

- general: a measure how likely an outcome is
- frequentist interpretation:
the expected number an outcome appears
if an experiment is repeated often
- bets interpretation:
the proportion of money someone bets
on a single outcome

Where do probabilities come from?

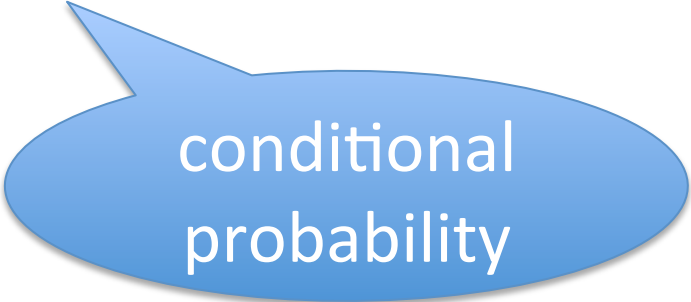
- mathematical concept
- to model random process
(relation between cause and result is not completely known)
 - metaphysical randomness
(cause does not completely determine the result)
 - I am not interested in/I do not know the cause
 - No scientist (currently) knows the exact cause
(but given enough time & money, one could find out)
 - The cause lies outside the realm of science

How to define a probability space

- Example: throw a die
- Possible outcomes: $\Omega = \{\square, \square, \square, \square, \square, \square\}$
- Probability weight: $P(\square) = \frac{1}{6}$
 $P(\square) = \frac{1}{6}$
etc.

Notation

- $P(A)$ = probability that A happens
- $P(A,B)$ = probability that both A and B happen
- $P(A | B)$ = probability that A happens
under the condition
that B has happened
- $P(A | B) = P(A,B) / P(B)$



conditional
probability

Throw more dice

- How probable is an even outcome?
 - $P(\text{even}) = P(\text{☐}) + P(\text{☒}) + P(\text{☓}) = \frac{1}{2}$
- How probable is the outcome ☓, given that we know the outcome is even?
 - $P(\text{☓} | \text{even}) = P(\text{☓, even}) / P(\text{even}) = \frac{1}{6} / \frac{1}{2} = \frac{1}{3}$
 - $P(\text{even} | \text{☓}) = \underline{P}(\text{even, ☓}) / P(\text{☓}) = 1$

Another example

- Some process (e. g. solving a quiz) takes between 2 and 5 minutes, each duration D having equal probability.
- What is the probability that it takes exactly $D = 3.1415$ minutes?
- $1 = \sum_{x \in [2,5]} P(D = x) = \sum_{x \in [2,5]} p_0 = \infty \cdot p_0$
- and therefore $p_0 = 1 / \infty = 0$
- $P(D \leq 3) = \sum_{x \in [2,3]} p_0 = \sum_{x \in [2,3]} 0 = 0$

A red oval with a white border and a slight shadow, containing the text "Oops?" in white. It is positioned to the right of the list of equations.

A better definition

- assign probabilities to subsets of Ω in a systematic way
- A σ -algebra \mathcal{A} is a set of subsets:
 - $\Omega \in \mathcal{A}$
 - $A \in \mathcal{A} \rightarrow \Omega \setminus A \in \mathcal{A}$
 - $A_i \in \mathcal{A}$ for all $i = 1, 2, \dots \rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{A}$
- Generally: It is sensible to assign a probability to each set in the σ -algebra.

Example: Borel- σ -algebra

- $\Omega = \mathbb{R}$
- \mathcal{B} = the smallest σ -algebra that contains all intervals $[r,s)$, for $r,s \in \mathbb{R}$
- standard σ -algebra for the real numbers
- Émile Borel, French mathematician, 1871–1956, wrote *Le Hasard*

